

Cascaded Control of High-Frequency Bidirectional Multi-Phase Boost Converters Implemented on Low-Cost FPGA

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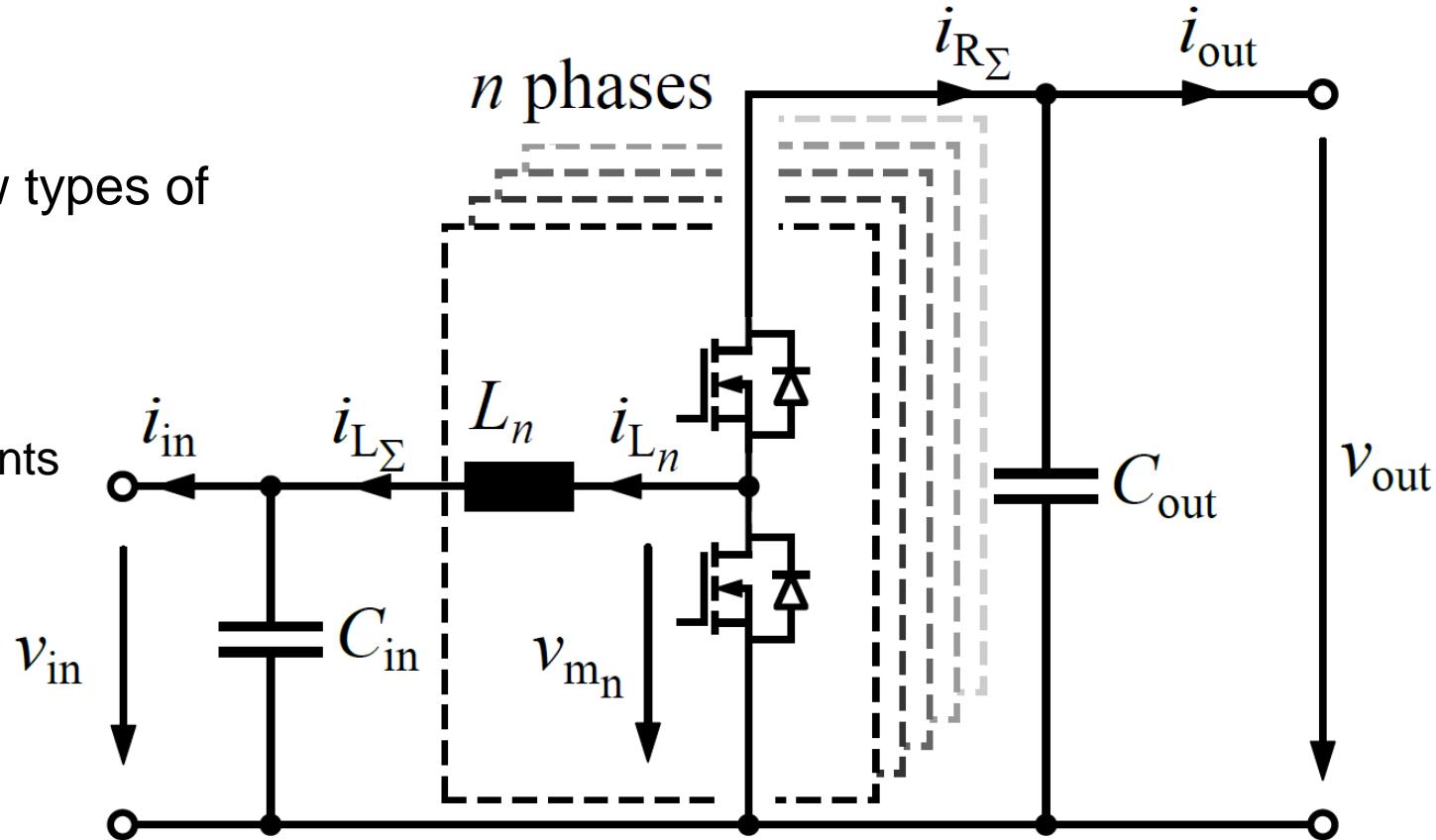
Motivation

- New wide-bandgap semiconductors provide:

- Lower switching losses
 - Higher switching frequencies

- Requirements for the control of these new types of fast-switching dc-dc converters:

- Control of n -phases
 - Low-cost control platform
 - Dynamic, thus minimizing passive components



Outline

- Motivation
- DC-DC Converter Specification
- Control Platform Prototype
- Cascaded Control Structure
- Experimental Results
- Conclusions

SiC DC-DC Converter Specification

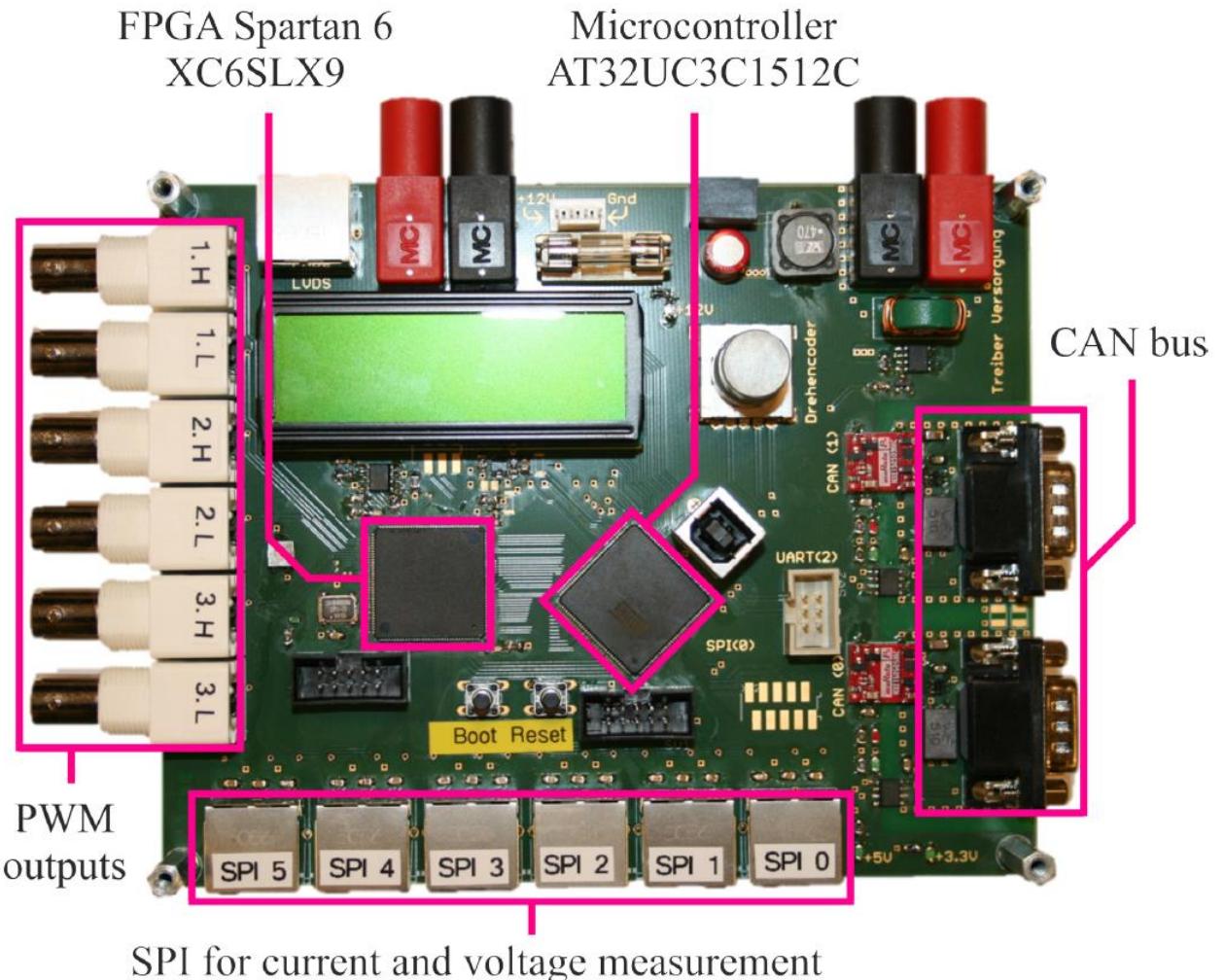
■ Key Parameters:

- Input voltage V_{in} = 80 V ... 500V
- Output voltage V_{out} = V_{in} ... 800V
- Switching frequency f_{sw} = 150 kHz
- Number of phases = 3
- Maximum output power = 42 kW
- Maximum phase current = 35 A

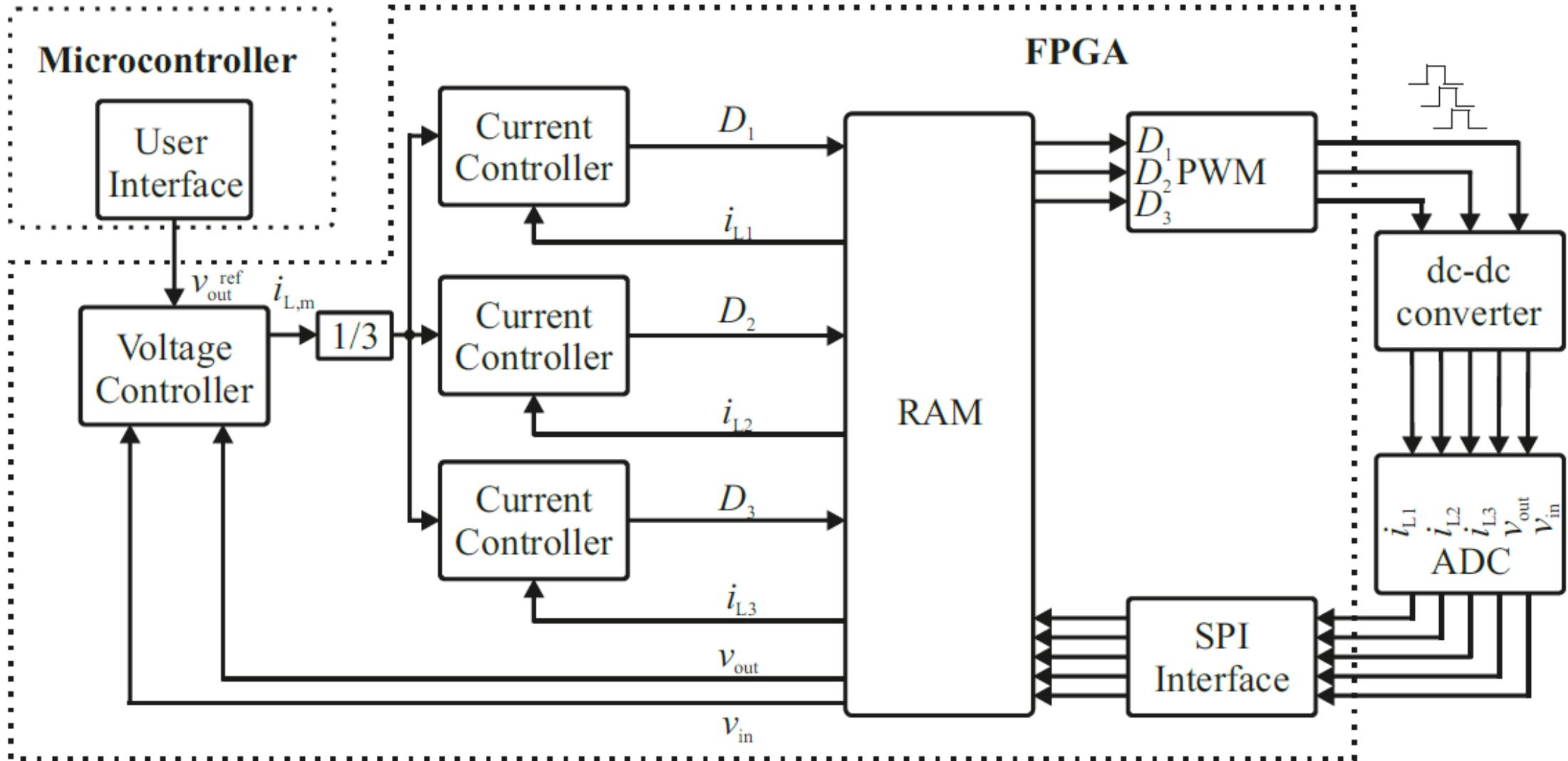


Control Platform Prototype

- Hybrid control board with an FPGA + µC
- Reference voltage can be set via
 - Manual user input
 - CAN-BUS
 - UART
- The three-phase control board can be scaled up to control a higher number of converter phases

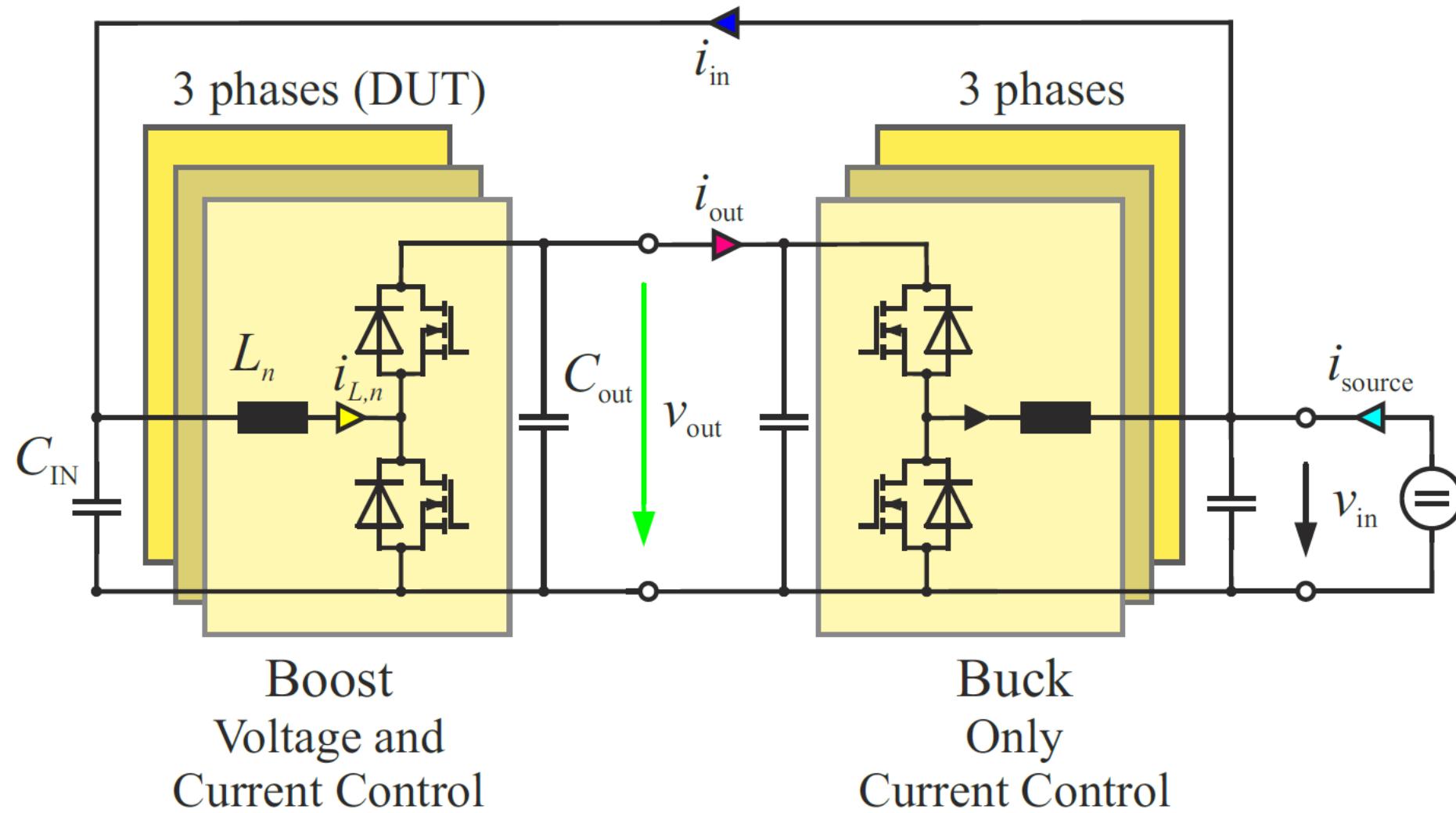


Control Platform Prototype



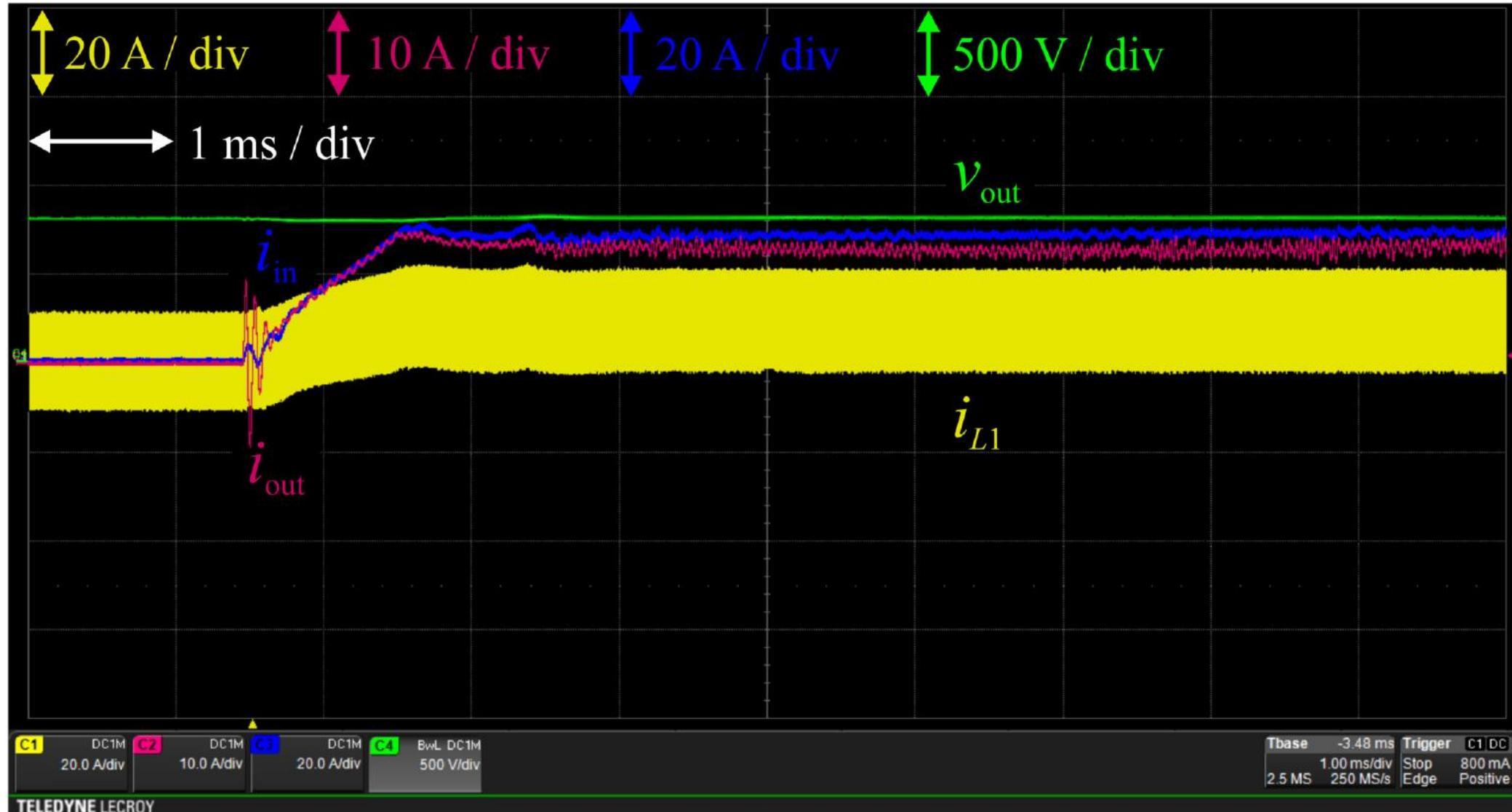
Experimental Results

Back-to-Back Connection of two DC-DC Converters



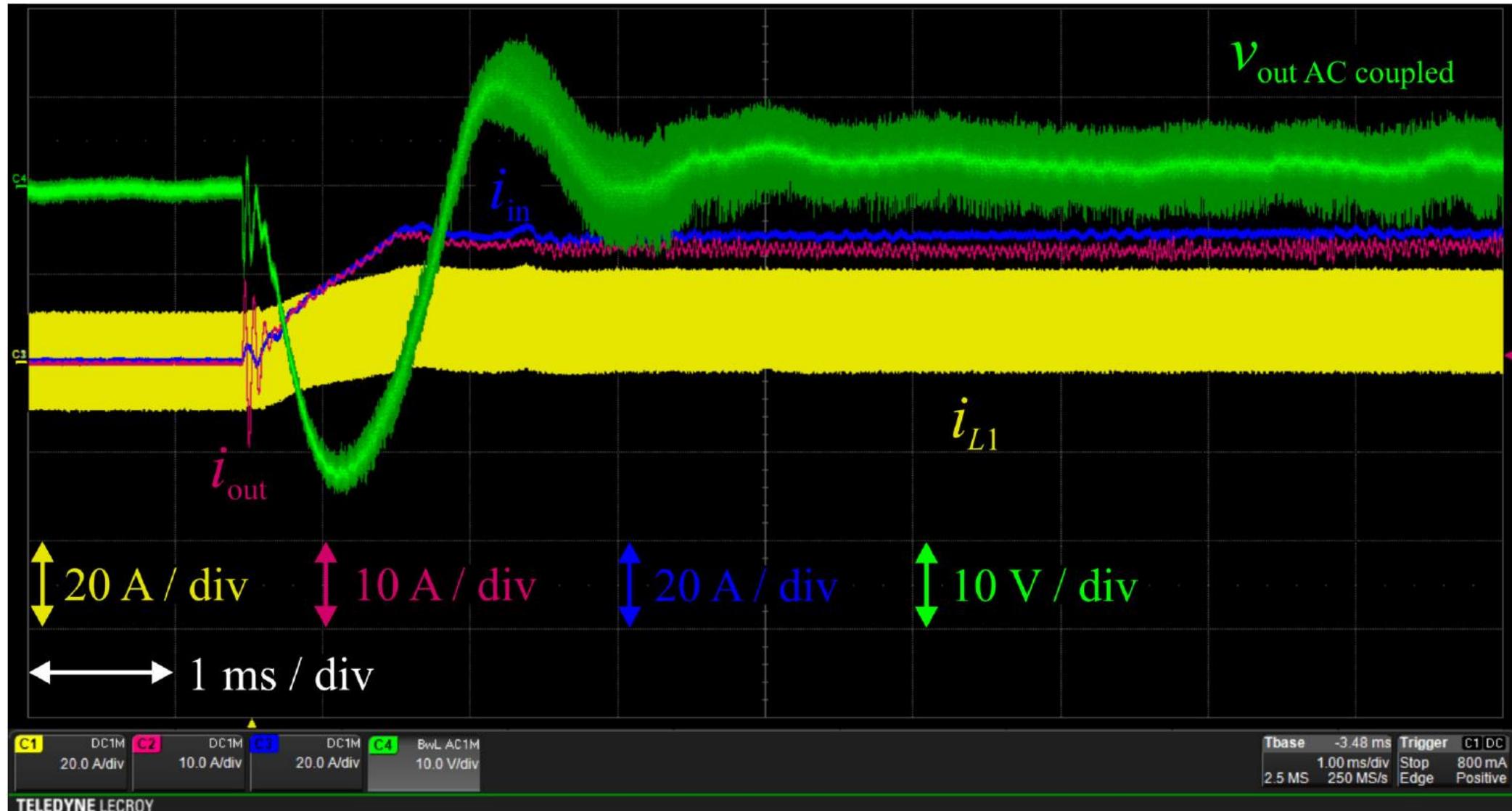
Experimental Results

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Experimental Results

Back-to-Back Connection of two DC-DC Converters



Conclusions

- A high-bandwidth model-based cascaded control of multi-phase bidirectional boost converters operating at high switching frequencies has been introduced.
- The model-based control is executed synchronously to the switching frequency, resulting in high-bandwidth control dynamics that allow to minimize passive components and thus converter size.
- To achieve the required tremendous calculation effort for the control algorithm within one switching period, the control algorithms are implemented on an inexpensive Spartan-6 FPGA.
- Experimental results of a 42 kW 3-phase bidirectional SiC boost converter operated at 150 kHz were presented to demonstrate the performance of the control algorithm.

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Thank you for your attention!